

2. [10] Rods and Planes 棒与面

(a) Gravitational Field Generated by Rods 由细棒产生的引力场

- (ai) [1] Find the magnitude of gravitational field at a distance d from an infinitely long thin rod with mass per unit length λ .
- (aii) [3] Consider 2026 infinitely long thin rods oriented along the z axis, each with mass per unit length λ . The 2026 rods are on positions $(x_n, y_n) = \left(r_0 \cos \frac{2n\pi}{2026}, r_0 \sin \frac{2n\pi}{2026}\right)$, where $0 \leq n \leq 2025$. Find the net force on a point mass with mass m located at $(d, 0)$. (Hint: You can consider the complex roots of the polynomial: $(z + d)^{2026} - r_0^{2026} = 0$)
- (aiii) [1] Suppose the small point mass is constrained to only move along the x axis, determine if it will oscillate around the origin. (Just answer yes or no)

(ai) [1] 求距离一根线质量密度为 λ 的“无限长细棒”距离 d 处的引力场强度。

(aii) [3] 考虑 2026 根沿 z 方向排列的无限长细棒，每根细棒的质量线密度皆为 λ 。第 n 根细棒在平面上的位置为 $(x_n, y_n) = \left(r_0 \cos \frac{2n\pi}{2026}, r_0 \sin \frac{2n\pi}{2026}\right)$ 。求质量为 m 的质点在 $(d, 0)$ 点的合外力。

(提示：你可以考虑多项式 $(z + d)^{2026} - r_0^{2026} = 0$ 的复根)

(aiii) [1] 若该质点仅被限制在 x 轴运动，判断其会否在原点附近来回移动。（只需回答“是”或“否”）

(b) Gravitational Field Generated by a Plate. 由平板产生的引力场

(bi) [1] Consider an infinite horizontal plane with mass per unit area σ , find the magnitude of gravitational field a distance h above the plate.

(bii) [2] Consider a flat and horizontal circular plate with radius R and total mass m . Find the magnitude of gravitational field due to the plate at a distance $h = R$ above the center of the plate if the plate has uniform density.

(Hint: $\int_0^1 \frac{x dx}{(1+x^2)^{\frac{3}{2}}} = 1 - \frac{\sqrt{2}}{2}$)

(biii) [2] Consider a horizontal, equilateral triangular plate of mass m , and side length a . Find the magnitude of gravitational field due to the plate at a distance $h = \frac{\sqrt{6}a}{12}$ above the centroid of the plate if the plate has uniform density. (Hint: The distance from the center of a regular tetrahedron to any of its face is $\frac{\sqrt{6}}{12}$ of the side length of each face.)

(bi) [1] 考虑一张无限大的水平平板，其面质量密度为 σ ，求在距离平板高度为 h 处的引力场强度。

(bii) [2] 考虑一张水平放置的圆形平板，半径为 R ，质量平均分佈，总质量为 m 。求在距离平板中心高度 $h = R$ 处，由该平板产生的引力场强度。（提示： $\int_0^1 \frac{x dx}{(1+x^2)^{\frac{3}{2}}} = 1 - \frac{\sqrt{2}}{2}$ ）

(biii) [2] 考虑一个质量为 m 、边长为 a 的水平正三角形板。求位于平板质心正上方、高度 $h = \frac{\sqrt{6}a}{12}$ 处的引力场强度。（提示：正四面体的中心到任一面的距离为其边长的 $\frac{\sqrt{6}}{12}$ 。）

Solution:

(ai) By using Gauss' Law of gravitation, we can easily get

$$g = \frac{2G\lambda}{d}$$

(aii) Note that the G force caused by the rods are given by $F_n = \frac{2Gm\lambda}{d_n} \hat{d}_n$, where $\vec{d}_n$ is the position vector of the rod from the test charge.

Therefore, we can interpret each d_n as a complex number, where we know it will be a root of the equation $(z + d)^{2026} - r_0^{2026} = 0$.

Denote the complex conjugate of d_n as d_n^* , note that $d_n = d_{2026-n}^*$ for $n \neq 0$, and for $n = 0$, $d_0 = d_0^*$.

Notice how $\frac{2Gm\lambda}{d_n^*}$ has the argument same as d_n and absolute value $\frac{2Gm\lambda}{|d_n|}$, which is a perfect complex analogy for the gravitational force caused by a rod at d_n . Therefore, we have

$$\sum_{n=0}^{2025} \frac{1}{d_n^*} = \sum_{n=1}^{2026} \frac{1}{d_{2026-n}} = \sum_{n=0}^{2025} \frac{1}{d_n} = \frac{d_0 d_1 \dots d_{2023} + \dots + d_1 d_2 \dots d_{2024}}{d_0 d_1 \dots d_{2024}} \quad (1)$$

By considering the coefficients of the polynomial equation, we get

$$\sum_{n=0}^{2025} \frac{1}{d_n} = \frac{2026 x_0^{2025}}{r_0^{2026} - x_0^{2026}} \quad (2)$$

Therefore, the total force is

$$F = \sum_{n=0}^{2025} F_n = 2Gm\lambda \sum_{n=0}^{2025} \frac{1}{d_n} = \frac{4052Gm\lambda x_0^{2025}}{r_0^{2026} - x_0^{2026}} \quad (3)$$

The force only has component parallel to the x axis by symmetry, so a positive value here indicates a force towards the positive x direction.

(Detailed solution) By the Gauss' law, the gravitational force on the test mass is

$$\vec{F}_n = -\frac{2Gm\lambda}{d_n} \hat{d}_n = -2Gm\lambda \left(\frac{d_x}{d^2} \hat{x} + \frac{d_y}{d^2} \hat{y} \right)$$

where $\vec{d}_n$ is the position vector of the rod from the point mass and $\hat{d}_n$ is the unit vector.

$$\vec{d}_n = \left(r_0 \cos \frac{2n\pi}{2025} - x_0 \right) \hat{x} + r_0 \sin \frac{2n\pi}{2025} \hat{y}$$

Define the complex number $\tilde{d}_n$:

$$\tilde{d}_n = \left(r_0 \cos \frac{2n\pi}{2025} - x_0 \right) + i r_0 \sin \frac{2n\pi}{2025}$$

$$\Rightarrow F_x = -2Gm\lambda \frac{d_x}{d^2}, \quad F_y = -2Gm\lambda \frac{d_y}{d^2}$$

$$\tilde{F}_n = -2Gm\lambda \left(\frac{d_x}{d^2} + i \frac{d_y}{d^2} \right) = -2Gm\lambda \frac{1}{d_x - i d_y} = -2Gm\lambda \frac{1}{\tilde{d}_n^*}$$

The net complex force can be written as

$$\tilde{F}_{net} = -2Gm\lambda \sum_n \frac{1}{\tilde{d}_n^*}$$

Notice that $\{d_n\}$ are the complex roots of the 2026th order polynomial:

$$(z + d)^{2026} - r_0^{2026} = (z - \tilde{d}_0)(z - \tilde{d}_1) \dots (z - \tilde{d}_{2025}) = 0$$

$$\Rightarrow (-\tilde{d}_0)(-\tilde{d}_1) \dots (-\tilde{d}_{2025}) = x_0^{2026} - r_0^{2026}$$

$$\Rightarrow \tilde{d}_0 \tilde{d}_1 \dots \tilde{d}_{2025} = x_0^{2026} - r_0^{2026}$$

The coefficient of the linear term z:

$$2026x_0^{2025} = -(\tilde{d}_0 \tilde{d}_1 \dots \tilde{d}_{2024} + \dots + \tilde{d}_1 \tilde{d}_2 \dots \tilde{d}_{2025})$$

$$\sum_{n=0}^{2025} \frac{1}{\tilde{d}_n} = \frac{\tilde{d}_0 \tilde{d}_1 \dots \tilde{d}_{2024} + \dots + \tilde{d}_1 \tilde{d}_2 \dots \tilde{d}_{2025}}{\tilde{d}_0 \tilde{d}_1 \dots \tilde{d}_{2025}} \quad (1)$$

By considering the coefficients of the polynomial equation, we get

$$\sum_{n=0}^{2025} \frac{1}{\tilde{d}_n} = \frac{2026x_0^{2025}}{r_0^{2026} - x_0^{2026}} = \sum_{n=0}^{2025} \frac{1}{\tilde{d}_n^*} \quad (2)$$

Therefore, the total force (on the x direction by symmetry) is

$$\vec{F} = \text{Re}(\tilde{F})\hat{x} + \text{Im}(\tilde{F})\hat{y} = \sum_{n=0}^{2025} F_n \hat{x} = \hat{x} 2Gm\lambda \sum_{n=0}^{2025} \frac{1}{d_n} = \frac{4052Gm\lambda x_0^{2025}}{r_0^{2026} - x_0^{2026}} \hat{x} \quad (3)$$

(aiii) Since $F \approx \frac{4052Gm\lambda x_0^{2025}}{r_0^{2026}} \geq 0$ for $x > 0$ (positive displacement), the force always points towards the positive x direction for a displacement towards the positive x direction, so there is **no oscillation possible**.

(bi) It is easy to tell that the force is independent of h and always **$g = 2\pi G\sigma$** by Gauss' law.

(bii) We can use integration to solve it, decompose the circular plate into rings.

For a thin ring of thickness dr and radius r , by symmetry, we know the gravitational field is pointing in vertical direction, so

$$dg = \frac{2Gmhrdr}{R^2(h^2 + r^2)^{\frac{3}{2}}}$$

Doing integration from $r = 0$ to $r = R$ gives

$$g = \int_0^R \frac{2Gmhr}{R^2(h^2 + r^2)^{\frac{3}{2}}} dr = \frac{2Gm}{R^2} \int_0^1 \frac{x dx}{(1 + x^2)^{\frac{3}{2}}} = \frac{(2 - \sqrt{2})Gm}{R^2}$$

(biii) Consider putting a test mass of mass M at a distance $h = \frac{\sqrt{6}a}{12}$ above the centroid of the plate. By symmetry, we can just consider

vertical force. The magnitude of upward gravitational force on the plate by the test mass is

$$F = \int_A \vec{g}_M(\vec{r}) \cdot \hat{n} dm$$

Where $\vec{g}_M$ is the gravitational field by the point mass at some location on the plate, $\vec{r}$.

Observe that $dm = \frac{m}{A} dA$ and $\int_A \vec{g}_M(\vec{r}) \cdot \hat{n} dA$ is just the gravitational flux through the plate. By the symmetry of the tetrahedron, we have

$$\int_A \vec{g}_M(\vec{r}) \cdot \hat{n} dA = \frac{1}{4} (4\pi GM) = \pi GM$$

Therefore, the total gravitational force is $F = \frac{\pi GMm}{A}$

By Newton's third law, the gravitational force on the test mass by the plate has the exact same magnitude

$$F' = \frac{\pi GMm}{A}$$

Therefore, the magnitude of gravitational field due to the plate at a distance $h = \frac{\sqrt{6}a}{12}$ above the centroid of the plate is just

$$g' = \frac{F'}{M} = \frac{\pi Gm}{A} = \frac{4\sqrt{3}\pi Gm}{3a^2}$$